

Differential Equations: Interacting Oscillators

モデル化とシミュレーション特論
2023 年度前期
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- 1 Coupled Harmonic Oscillators
- 2 Decomposing into normal modes
- 3 Kuramoto Model

Harmonic oscillator

- Ordinary expression

$$m \frac{d^2 x}{dt^2} = -kx \quad (1.1)$$

- Hamiltonian (energy): $p = mv$: momentum

$$H = \frac{p^2}{2m} + V \quad (1.2)$$

$$V = \frac{1}{2} kx^2 \quad (1.3)$$

$$\frac{dp}{dt} = -\frac{\partial H}{\partial x} = -\frac{\partial V}{\partial x} = -kx \quad (1.4)$$

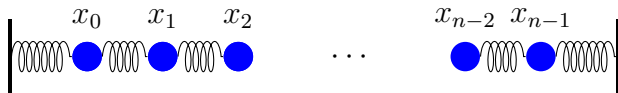
$$m \frac{dv}{dt} = -kx$$

$$\frac{dx}{dt} = \frac{\partial H}{\partial p} = \frac{p}{m} \quad (1.5)$$

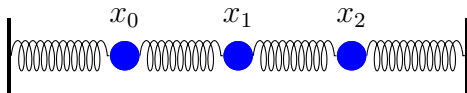
$$\frac{dx}{dt} = v$$

Coupled Harmonic Oscillators: Model

- Connecting n particles of mass m with springs of natural length b .
 - x_i : position of i -th particle
 - $y_i = x_i - (i + 1)b$: displacement from resting position of i -th particle



Three particles: Potential energy



Potential energy for each spring

$\frac{ky_0^2}{2}$	0th	
$\frac{k(y_1 - y_0)^2}{2}$	1st	
$\frac{k(y_2 - y_1)^2}{2}$	2nd	$V = \frac{k}{2} \left[y_0^2 + \sum_{i=1}^2 (y_i - y_{i-1})^2 + y_2^2 \right]$
$\frac{ky_2^2}{2}$	3rd	

(2.1)

Three particles: Equation of motion

$$m \frac{d^2 y_i}{dt^2} = -\frac{\partial V}{\partial y_i}, \quad V = \frac{k}{2} \left[y_0^2 + \sum_{i=1}^2 (y_i - y_{i-1})^2 + y_2^2 \right] \quad (2.2)$$

↓

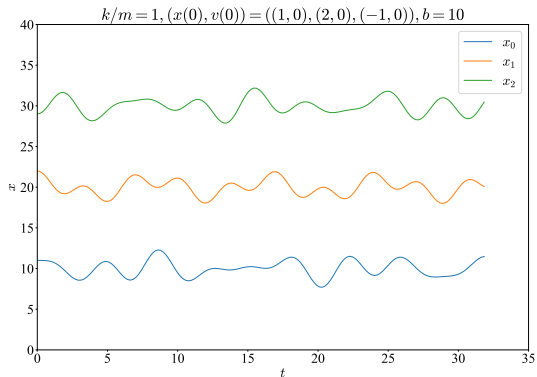
$$m \frac{d^2 y_0}{dt^2} = -k (2y_0 - y_1) \quad (2.3)$$

$$m \frac{d^2 y_1}{dt^2} = -k (-y_0 + 2y_1 - y_2) \quad (2.4)$$

$$m \frac{d^2 y_2}{dt^2} = -k (-y_1 + 2y_2) \quad (2.5)$$

Three variables y_i are **linearly** coupled.

Numerical solutions



Do motions of particles look complicated?

Equation of motion in matrix form

$$m \frac{d^2}{dt^2} \begin{pmatrix} y_0 \\ y_1 \\ y_2 \end{pmatrix} = -k \begin{pmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{pmatrix} \begin{pmatrix} y_0 \\ y_1 \\ y_2 \end{pmatrix} = -kM\vec{y} \quad (3.1)$$

- λ : eigen values of M
- \vec{v}_λ : eigen vector belonging to λ

$$M\vec{v}_\lambda = \lambda\vec{v}_\lambda \quad (3.2)$$

Eigen values of M

$$\begin{vmatrix} 2 - \lambda & -1 & 0 \\ -1 & 2 - \lambda & -1 \\ 0 & -1 & 2 - \lambda \end{vmatrix} = (2 - \lambda) [(2 - \lambda)^2 - 2] = 0 \quad (3.3)$$

$$\lambda_0 = 2 \quad (3.4)$$

$$\lambda_{\pm} = 2 \pm \sqrt{2} \quad (3.5)$$

Orthonormal eigen vectors of M

$$\lambda_0 = 2$$

$$\begin{pmatrix} 0 & -1 & 0 \\ -1 & 0 & -1 \\ 0 & -1 & 0 \end{pmatrix} \begin{pmatrix} y_0 \\ y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Rightarrow \vec{v}_0 = \frac{\sqrt{2}}{2} \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} \quad (3.6)$$

$$\lambda_{\pm} = 2 \pm \sqrt{2}$$

$$\begin{pmatrix} \mp\sqrt{2} & -1 & 0 \\ -1 & \mp\sqrt{2} & -1 \\ 0 & -1 & \mp\sqrt{2} \end{pmatrix} \begin{pmatrix} y_0 \\ y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Rightarrow \vec{v}_{\pm} = \frac{1}{2} \begin{pmatrix} 1 \\ \mp\sqrt{2} \\ 1 \end{pmatrix} \quad (3.7)$$

Solutions with eigen vectors

Express \vec{y} in linear combination of eigen vectors. Coefficients z_λ are functions of t .

$$\begin{pmatrix} y_0 \\ y_1 \\ y_2 \end{pmatrix} = z_+ \vec{v}_+ + z_0 \vec{v}_0 + z_- \vec{v}_- \quad (3.8)$$

$$z_\lambda = \vec{v}_\lambda \cdot \begin{pmatrix} y_0 \\ y_1 \\ y_2 \end{pmatrix} \quad (3.9)$$

$$z_0 = \frac{\sqrt{2}}{2} (y_0 - y_2) \quad (3.10)$$

$$z_\pm = \frac{1}{2} \left(y_0 \mp \sqrt{2} y_1 + y_2 \right) \quad (3.11)$$

Equation of motion with eiven vectors

• LHS

$$\begin{aligned}
 m \frac{d^2}{dt^2} \begin{pmatrix} y_0 \\ y_1 \\ y_2 \end{pmatrix} &= m \frac{d^2}{dt^2} (z_+ \vec{v}_+ + z_0 \vec{v}_0 + z_- \vec{v}_-) \\
 &= m \frac{d^2 z_+}{dt^2} \vec{v}_+ + m \frac{d^2 z_0}{dt^2} \vec{v}_0 + m \frac{d^2 z_-}{dt^2} \vec{v}_-
 \end{aligned}$$

• RHS

$$\begin{aligned}
 -kM \begin{pmatrix} y_0 \\ y_1 \\ y_2 \end{pmatrix} &= -kM (z_+ \vec{v}_+ + z_0 \vec{v}_0 + z_- \vec{v}_-) \\
 &= -k (\lambda_+ z_+ \vec{v}_+ + \lambda_0 z_0 \vec{v}_0 + \lambda_- z_- \vec{v}_-)
 \end{aligned}$$

Equation of motion for each mode

- harmonic oscillator with $\omega_\lambda = \sqrt{k\lambda/m}$

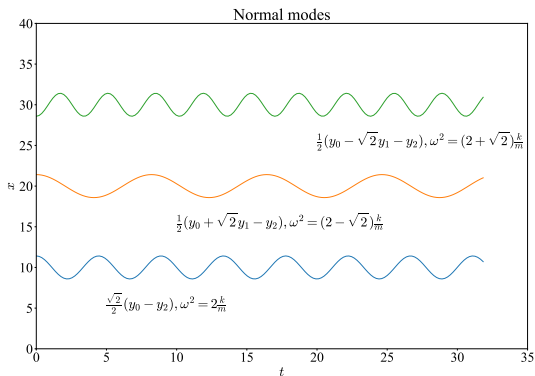
$$m \frac{d^2 z_\lambda}{dt^2} = -k\lambda z_\lambda$$

- oscillators with three different angular velocity

$$m \frac{d^2 z_0}{dt^2} = -2kz_0$$

$$m \frac{d^2 z_\pm}{dt^2} = -k(2 \pm \sqrt{2})z_\pm$$

Motions of eigen modes



Solutions with eigen modes

$$y_0 = \frac{1}{2} (z_+ + \sqrt{2}z_0 + z_-)$$

$$y_1 = -\frac{\sqrt{2}}{2} (z_+ - z_-)$$

$$y_2 = \frac{1}{2} (z_+ - \sqrt{2}z_0 + z_-)$$

Constructor in Java code

```

1  equation = (double xx, double[] yy) -> {
2      double dy[] = new double[2 * numOscillators];
3      //0-th particle
4      {
5          int i = 0;
6          int j = 2 * i;
7          dy[j] = yy[j + 1];
8          dy[j + 1] = -k * (2 * yy[j] - yy[j + 2]);
9      }
10     //particles between 1st to n-2-th
11     for (int i = 1; i < numOscillators - 1; i++) {
12         int j = 2 * i;
13         dy[j] = yy[j + 1];
14         dy[j + 1] = -k * (-yy[j - 2] + 2 * yy[j] - yy[j + 2]);
15     }
16     //n-1-th particle
17     {
18         int i = numOscillators - 1;
19         int j = 2 * i;
20         dy[j] = yy[j + 1];
21         dy[j + 1] = -k * (-yy[j - 2] + 2 * yy[j]);
22     }
23     return dy;
24 };

```

Synchronization

- fire flies
<https://www.youtube.com/watch?v=WMIXp8H8364>
- metronomes
<https://www.youtube.com/watch?v=JWToUATLGzs>
- pendulum clocks
Found occasionally by Christiaan Huygens in 1665

Kuramoto Model

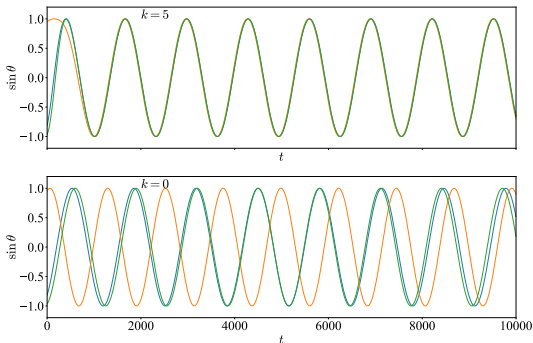
- Fundamental model for synchronization.
- N oscillators interact through their phase differences.

$$\frac{d\theta_i}{dt} = \omega_i + \frac{k}{N} \sum_j \sin(\theta_j - \theta_i) \quad (4.1)$$

Description in Kuramoto.java

```
1 equation = (double tt, double yy[]) -> {
2     double dy[] = new double[n];
3     for (int i = 0; i < n; i++) {
4         dy[i] = omega[i];
5         for (int j = 0; j < n; j++) {
6             dy[i] += (k / n) * Math.sin(yy[j] - yy[i]);
7         }
8     }
9     return dy;
10 };
```

Three oscillators



- Not Synchronize with $k = 0$
- Synchronize with $k = 5$

Order Parameter

$$R = \frac{1}{N} \sum_i e^{i\theta_i} \quad (4.2)$$

